



# ADVANCED DATA STRUCTURES AND ALGORITHMS

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**2015 – 2016**

# What this Lecture is about:

- ⚙ Graph Traversals (Search)
- ⚙ Breadth-first search
- ⚙ BFS: Level-by-level traversal
- ⚙ BFS for general graphs
- ⚙ Handling vertices
- ⚙ Interesting features of BFS
- ⚙ Interesting features of BFS



# Graph Traversals (Search)

- We have covered some of these with binary trees
  - **Breadth-first search (BFS)** 
  - **Depth-first search (DFS)** 
- A traversal (search):
  - An algorithm for systematically exploring a graph
  - Visiting (all) vertices
  - Until finding a goal vertex or until no more vertices



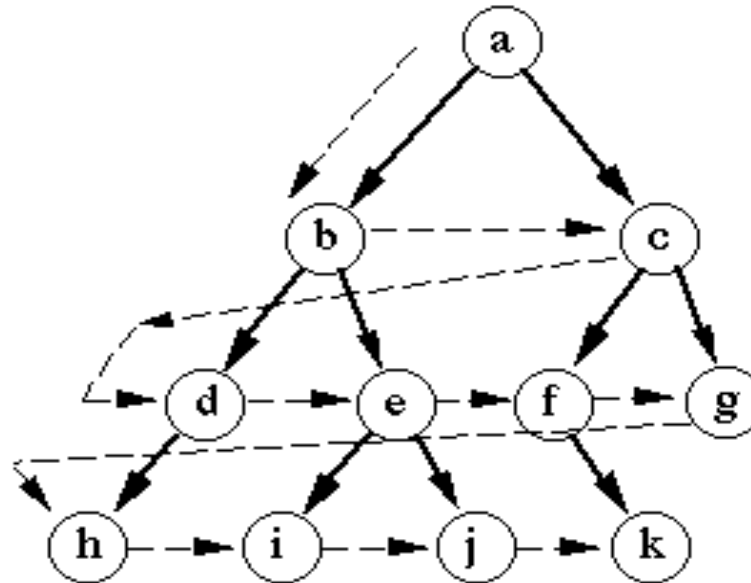
# Breadth-first search

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- One of the simplest algorithms
- Also one of the most important
  - It forms the basis for MANY graph algorithms

# BFS: Level-by-level traversal

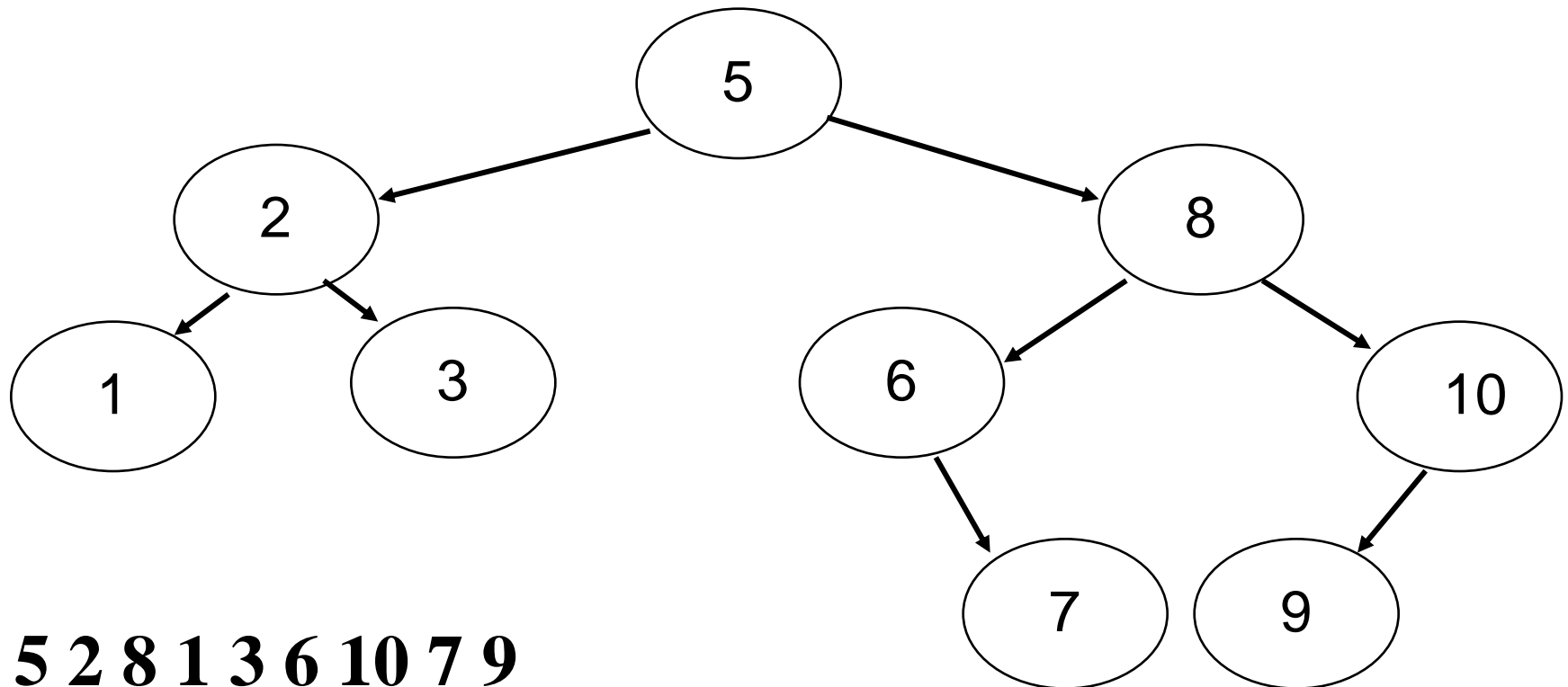
- Given a starting vertex  $s$
- Visit all vertices at increasing distance from  $s$ 
  - Visit all vertices at distance  $k$  from  $s$
  - Then visit all vertices at distance  $k+1$  from  $s$
  - Then ....



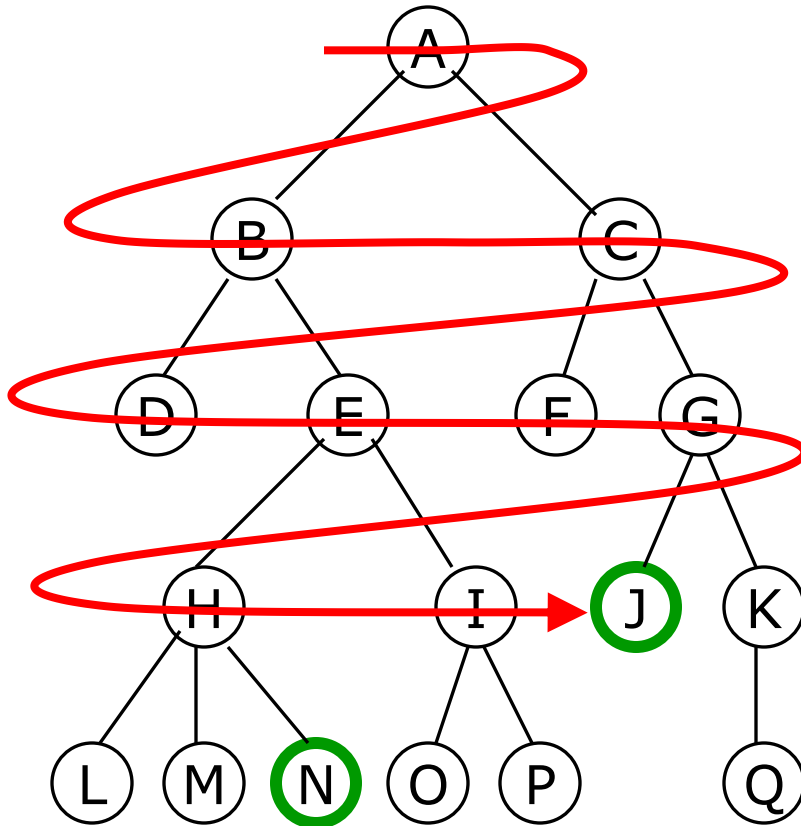
**Breadth-first search**

# BFS in a binary tree (reminder)

BFS: visit all siblings before their descendents

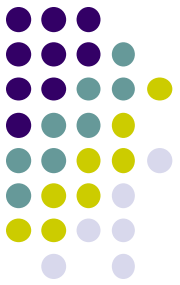


# Breadth-first searching

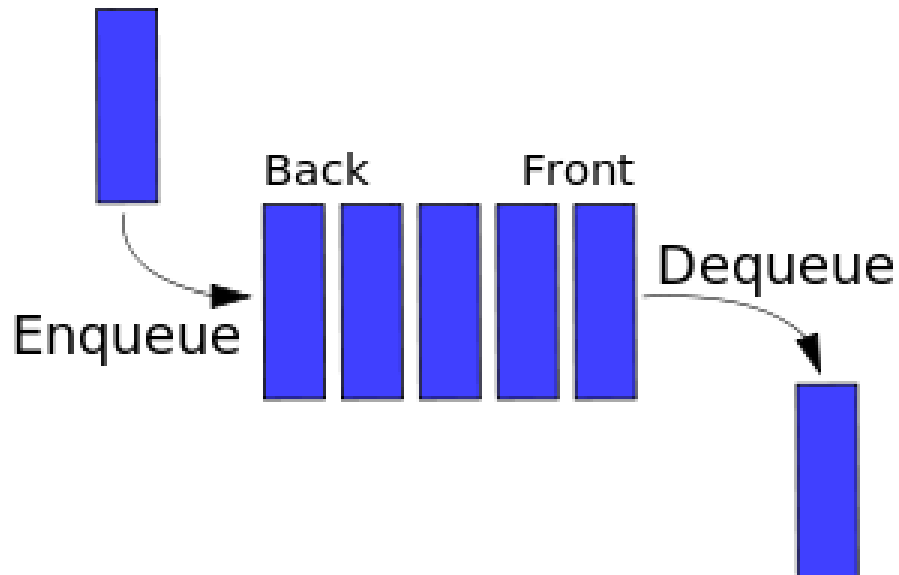


- Node are explored in the order  
A B C D E F G H I J K L M N  
O P Q
- J will be found before N

# Queue



The queue is First-In-First-Out (FIFO) data structure.

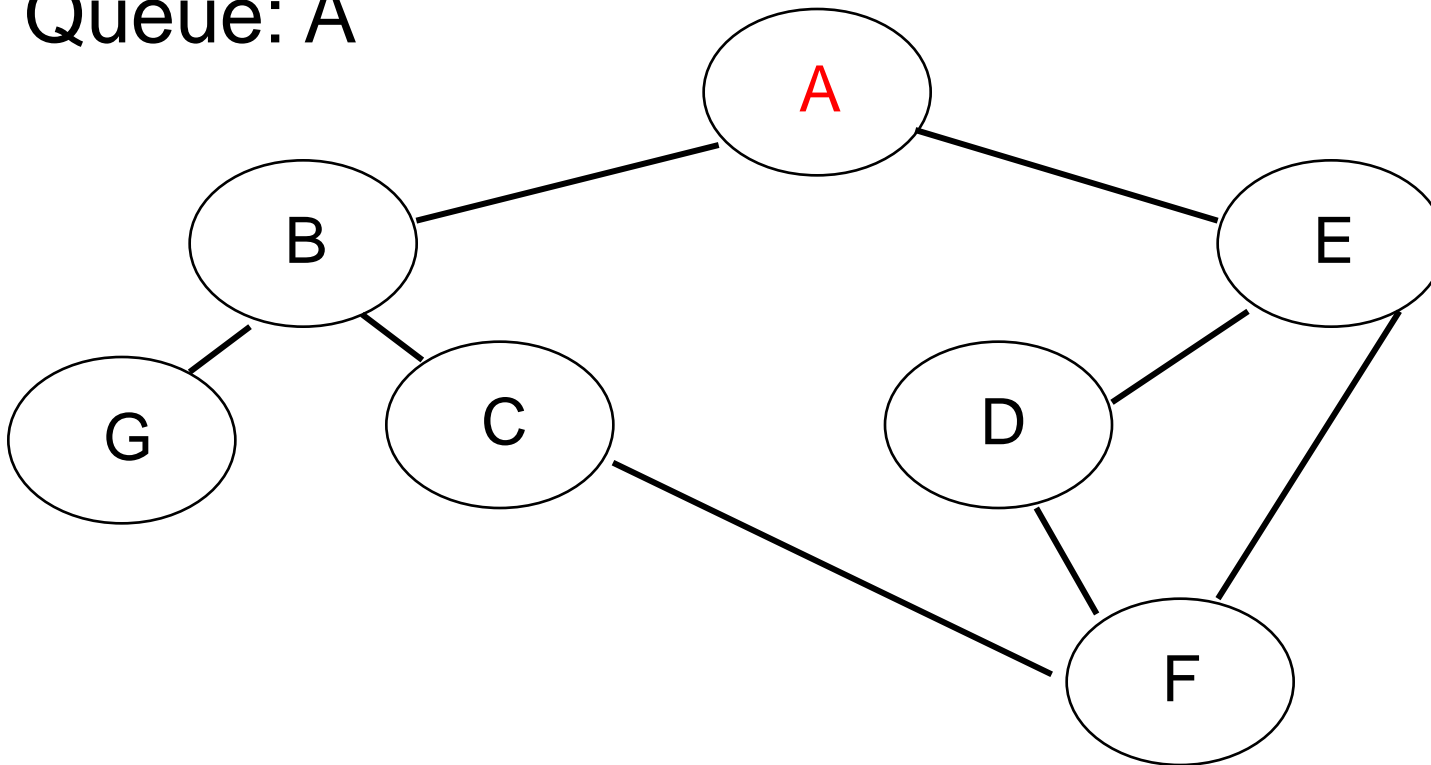






# BFS For General Graphs

Queue: A

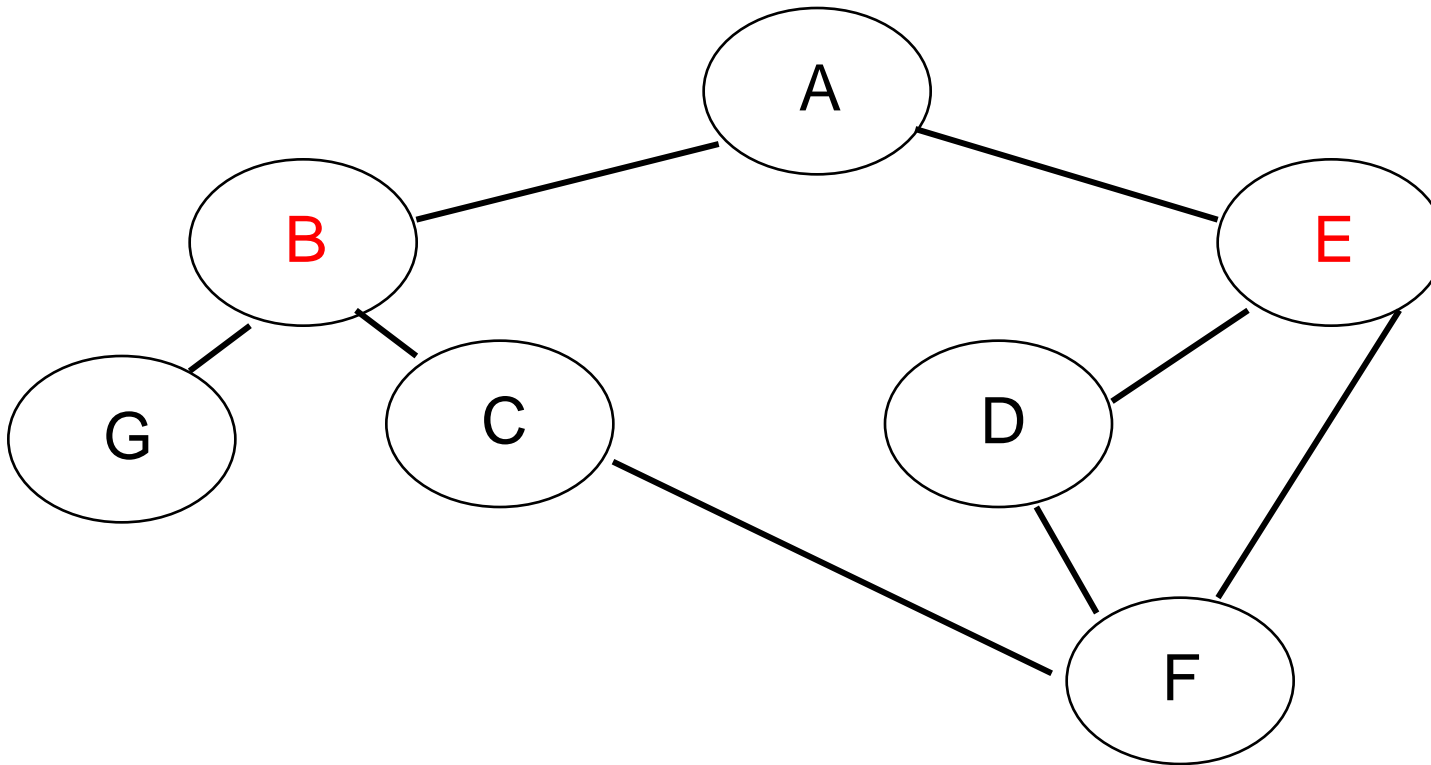


Start with **A**. Put in the queue (marked **red**)

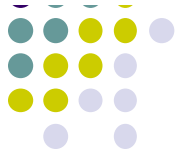
# Example.



Queue: A B E

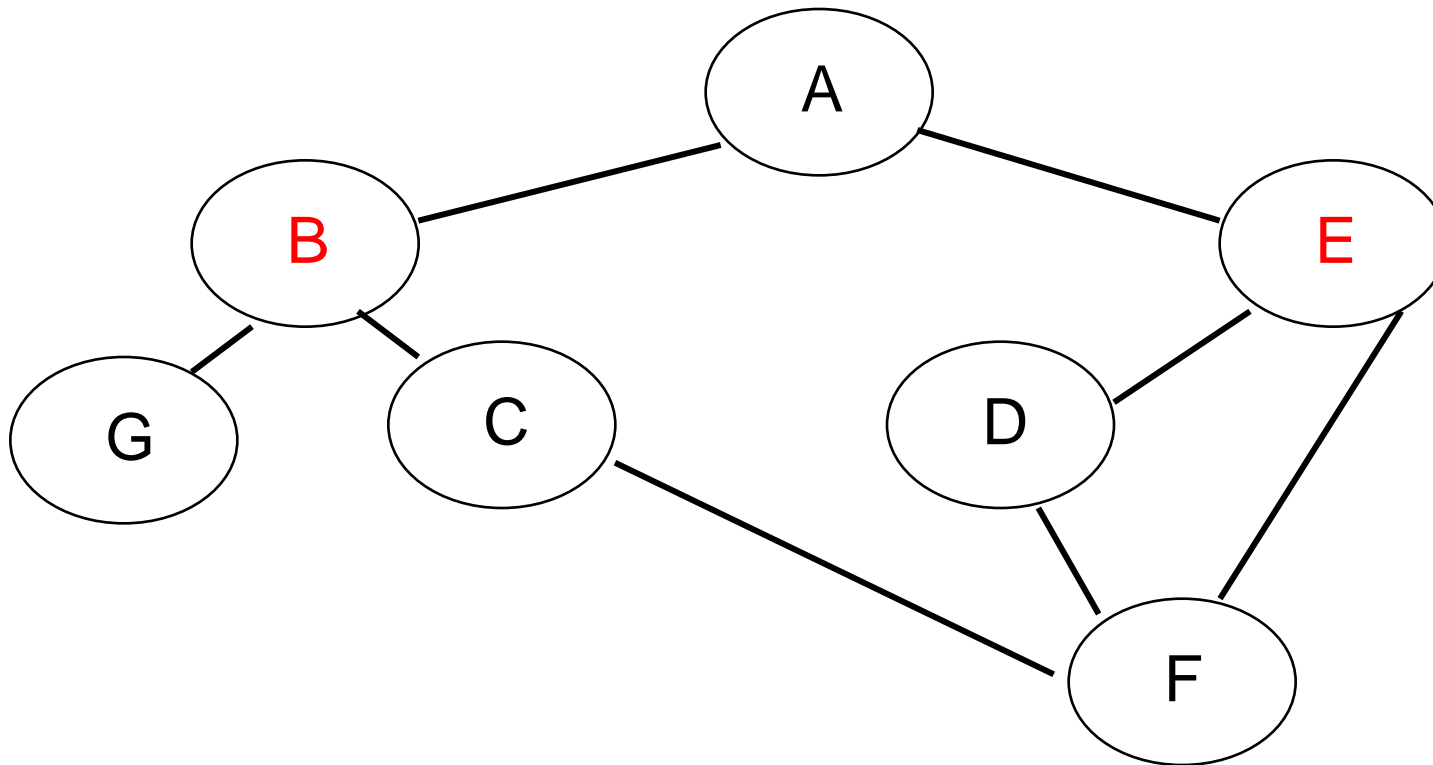


B and E are next



# Example.

Queue: A B E C G D F



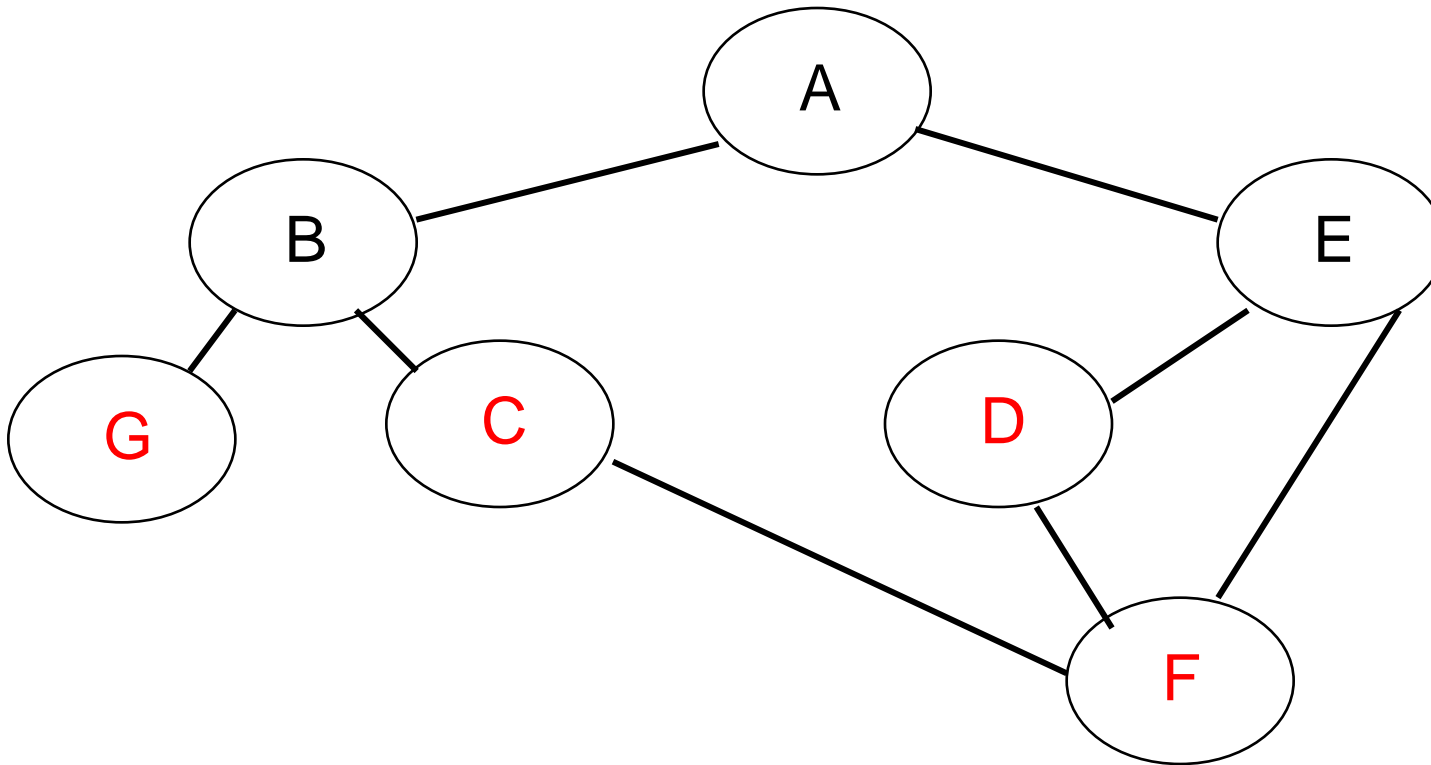
When we go to B, we put G and C in the queue

When we go to E, we put D and F in the queue



# Example.

Queue: A B E C G D F



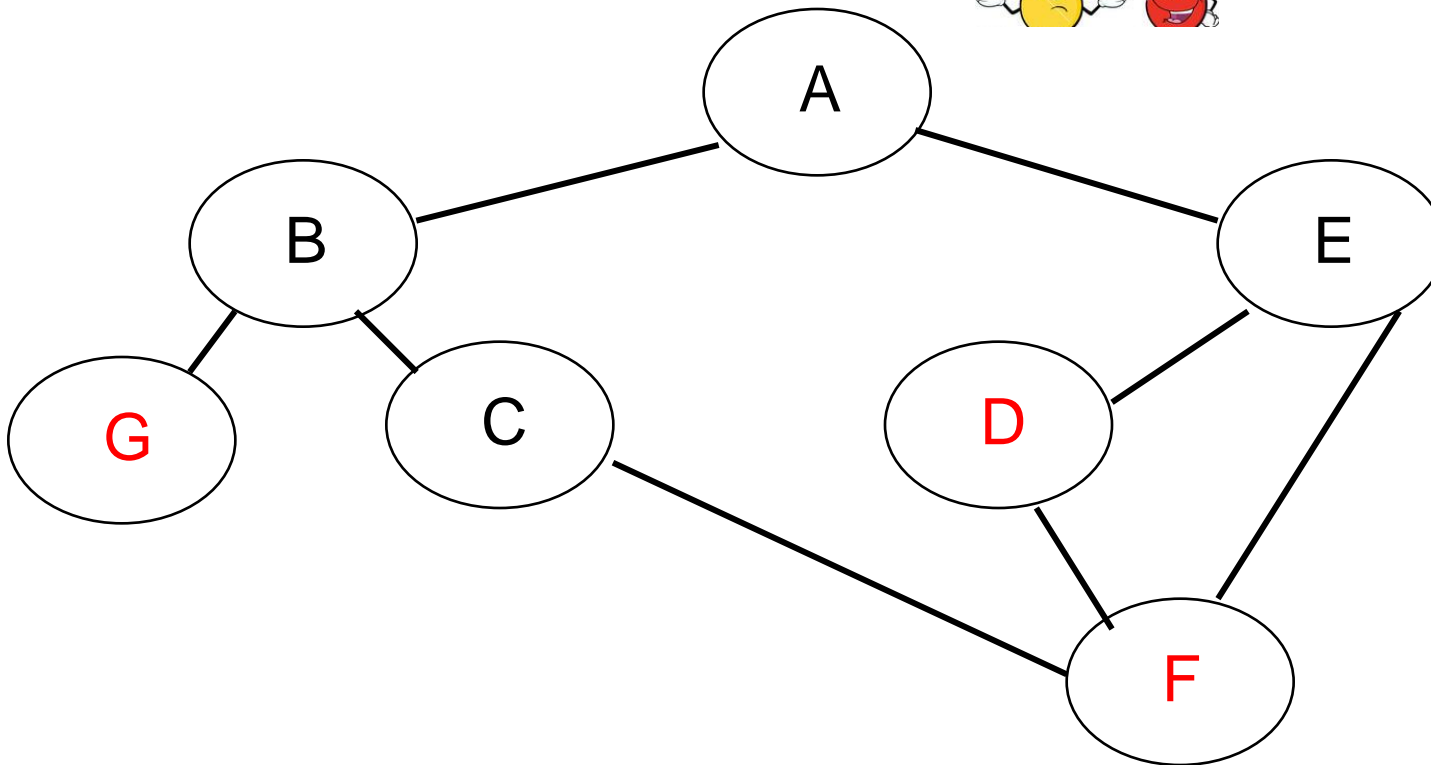
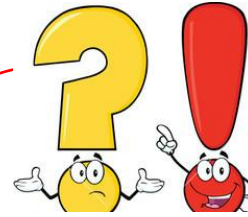
When we go to B, we put G and C in the queue

When we go to E, we put D and F in the queue



# Example.

Queue: A B E C G D F F



Suppose we now want to expand C.  
We put F in the queue again!



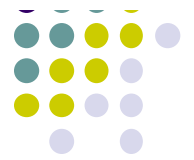
# Generalizing BFS

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- Cycles:
- We need to save auxiliary information
- Each node needs to be marked
  - Visited: No need to be put on queue
  - Not visited: Put on queue when found

What about assuming only two children vertices?

- Need to put **all** adjacent vertices in queue



# The general BFS algorithm

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- Each vertex can be in one of three states:
  - **Unmarked and not on queue**
  - **Marked and on queue**
  - **Marked and off queue**
- The algorithm moves vertices between these states



# Handling vertices

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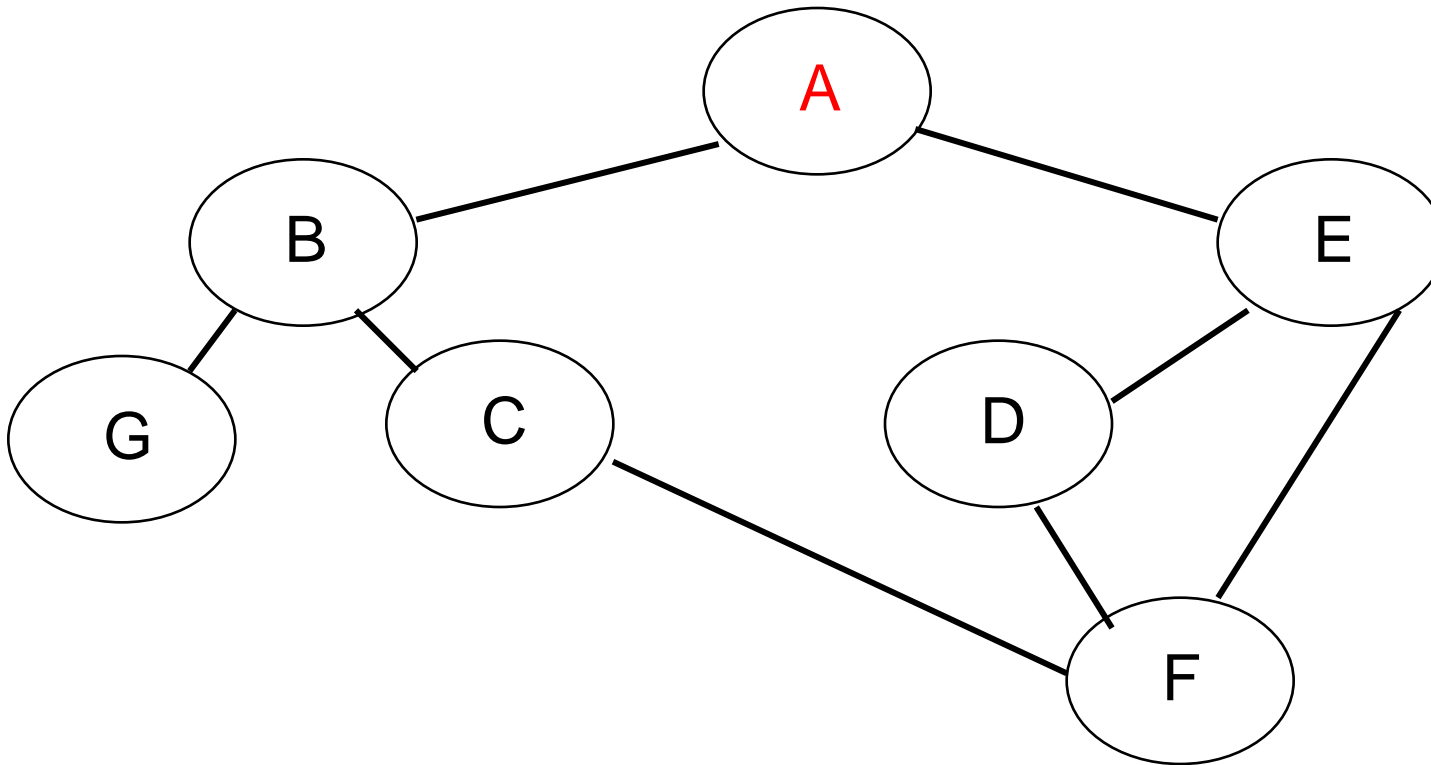
- Unmarked and not on queue:
  - Not reached yet
- Marked and on queue:
  - Known, but adjacent vertices not visited yet (possibly)
- Marked and off queue:
  - Known, all adjacent vertices on queue or done with



# Example



Queue: A



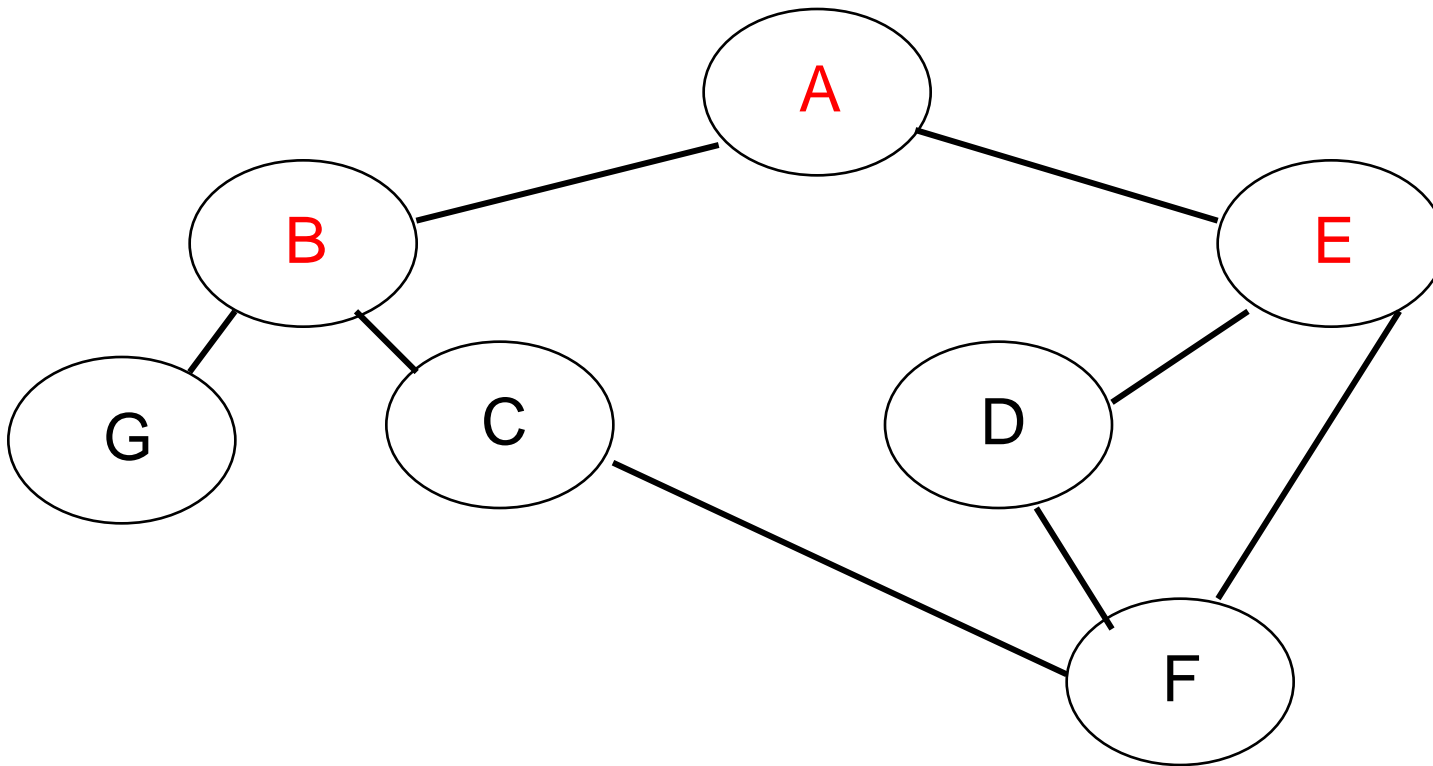
Start with A. Mark it.

# Example

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Queue: A B E



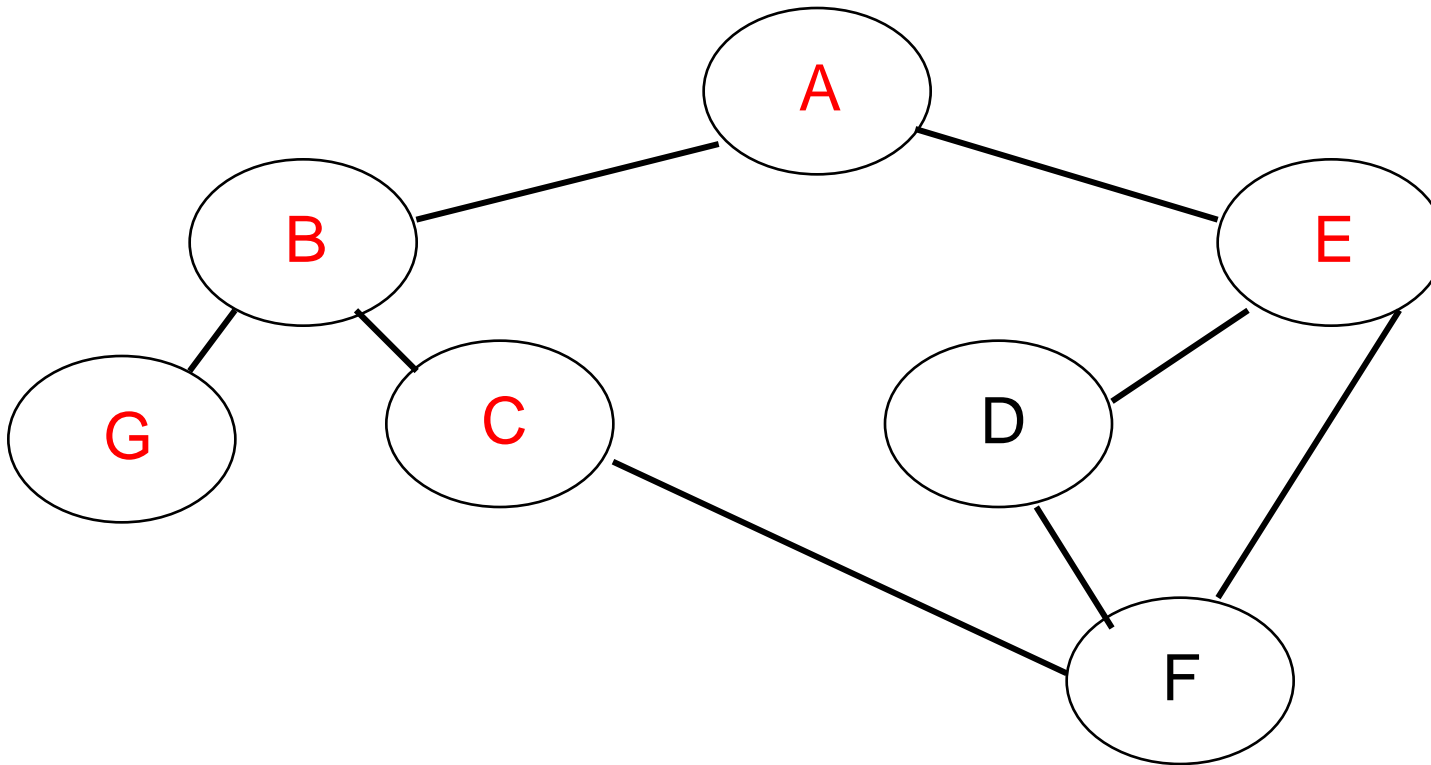
Expand A's adjacent vertices.

Mark them and put them in queue.

# Example



Queue: A B E C G

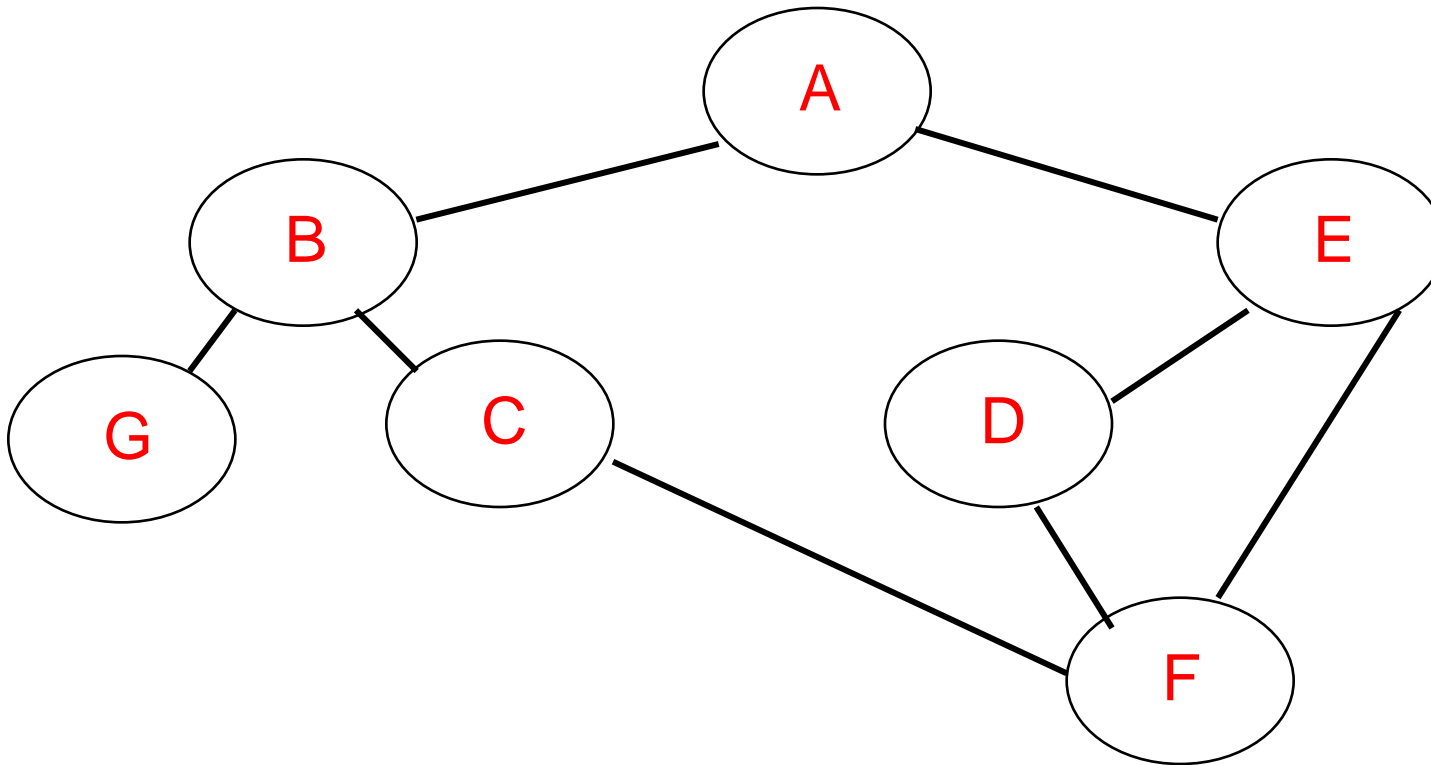


Now take B off queue, and queue its neighbors.

# Example



Queue: A B E C G D F



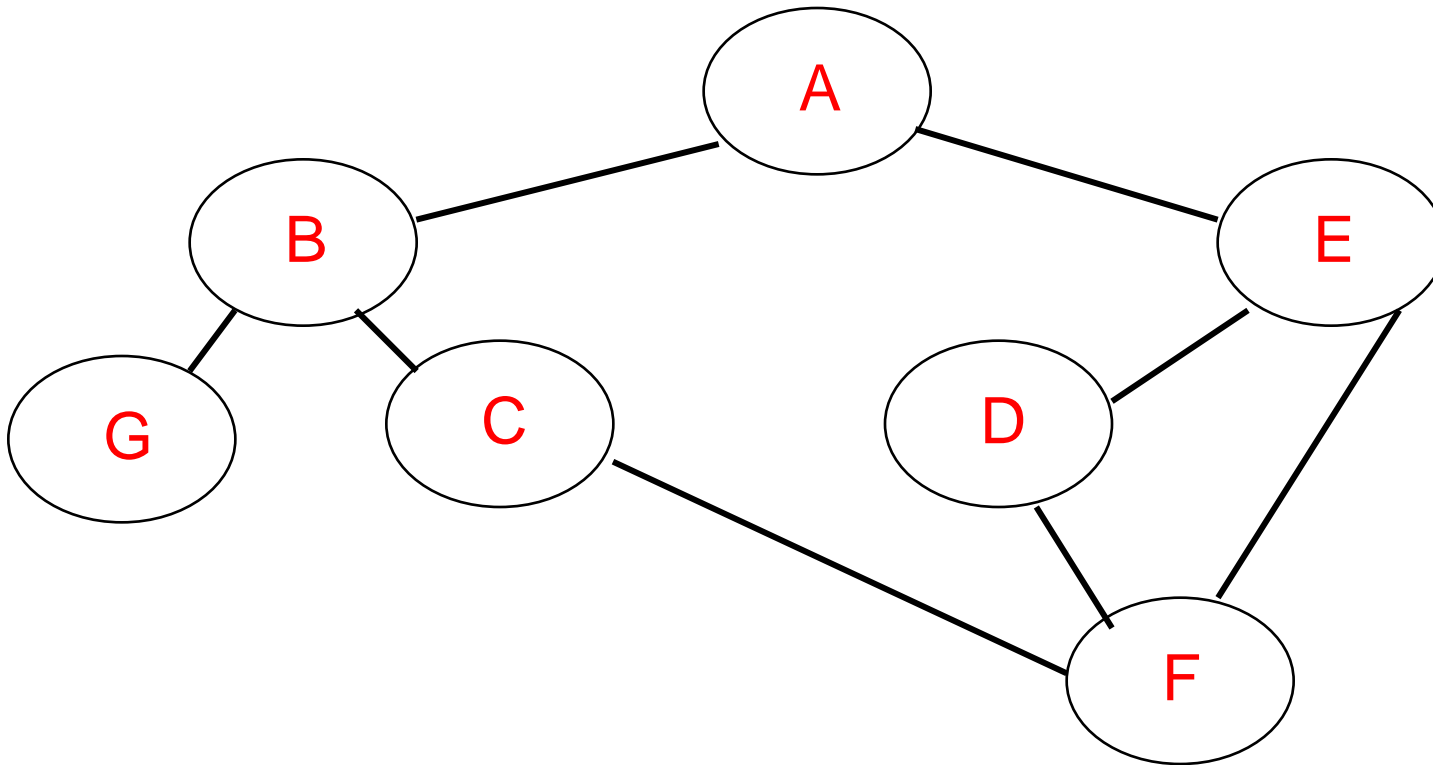
Do same with E.

# Example

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Queue: A B E C G D F



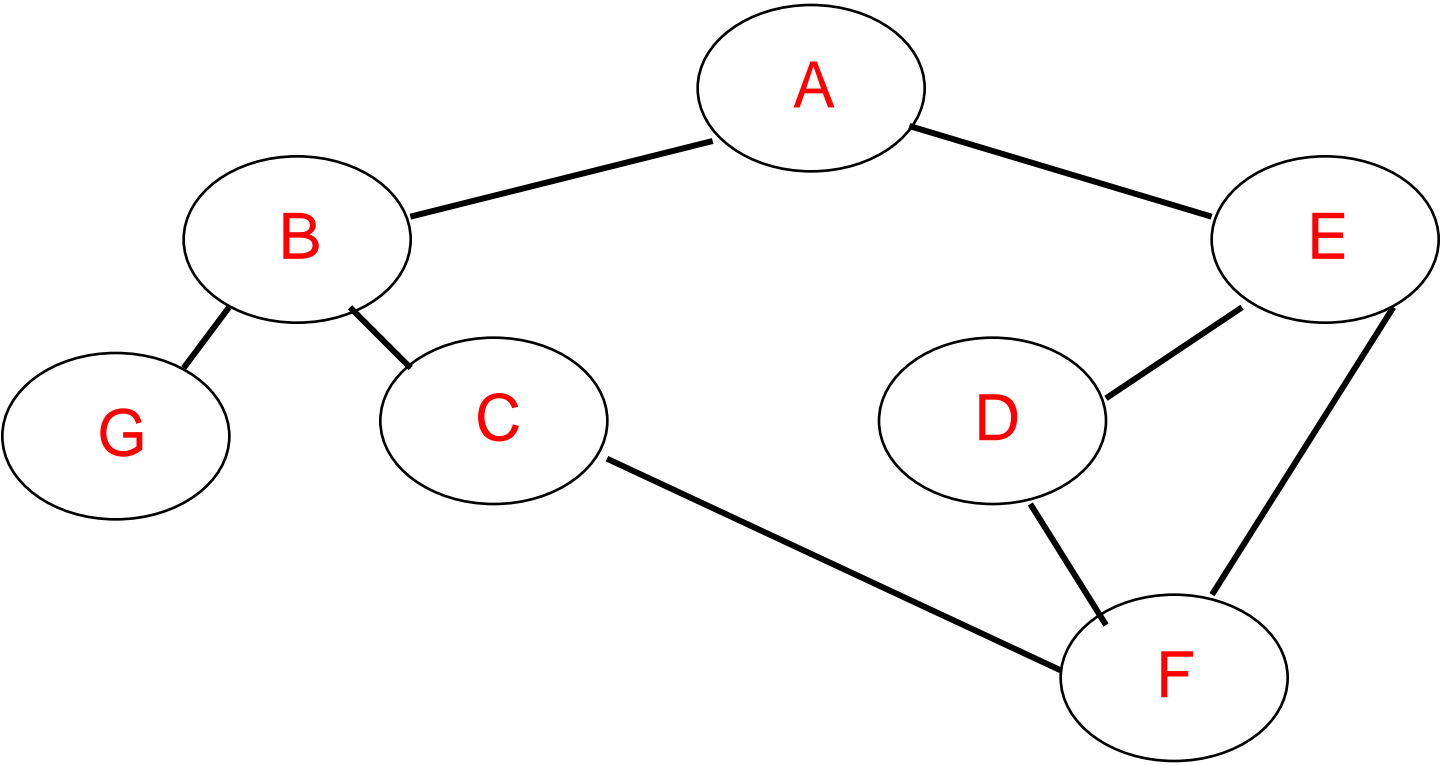
Visit C.

Its neighbor F is already marked, so not queued.

# Example



Queue: A B E C G D F

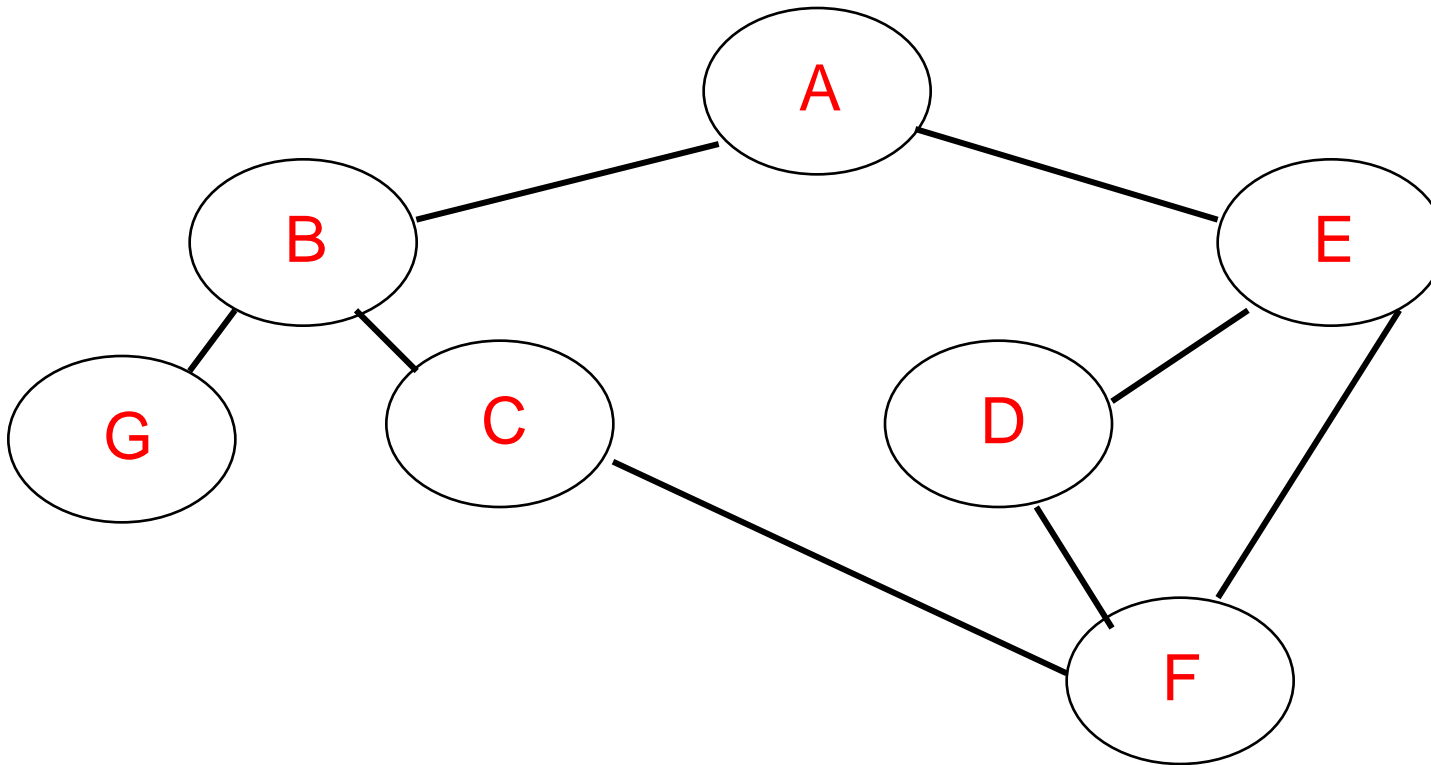


Visit G.

# Example



Queue: A B E C G D F

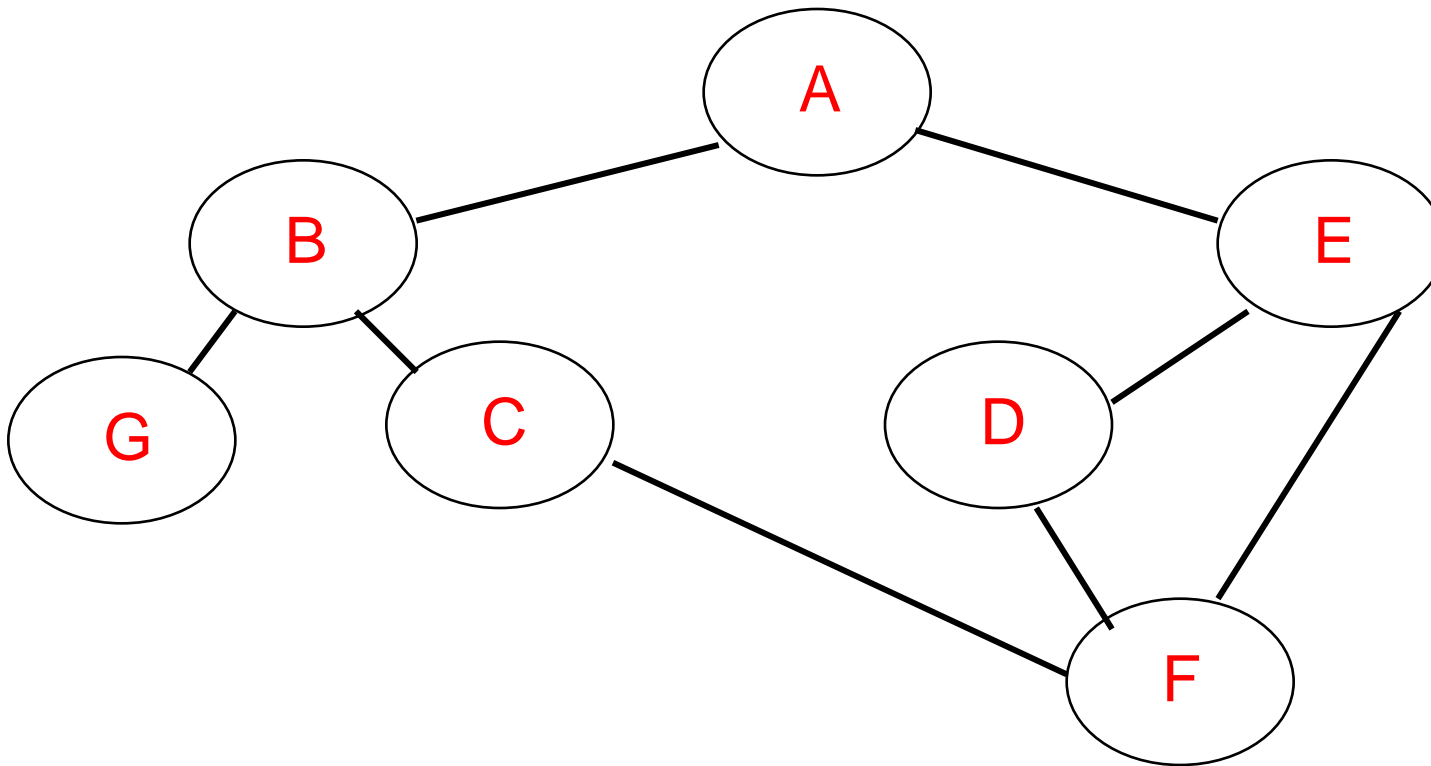


Visit D. F, E marked so not queued.

# Example



Queue: A B E C G D F



Visit F.

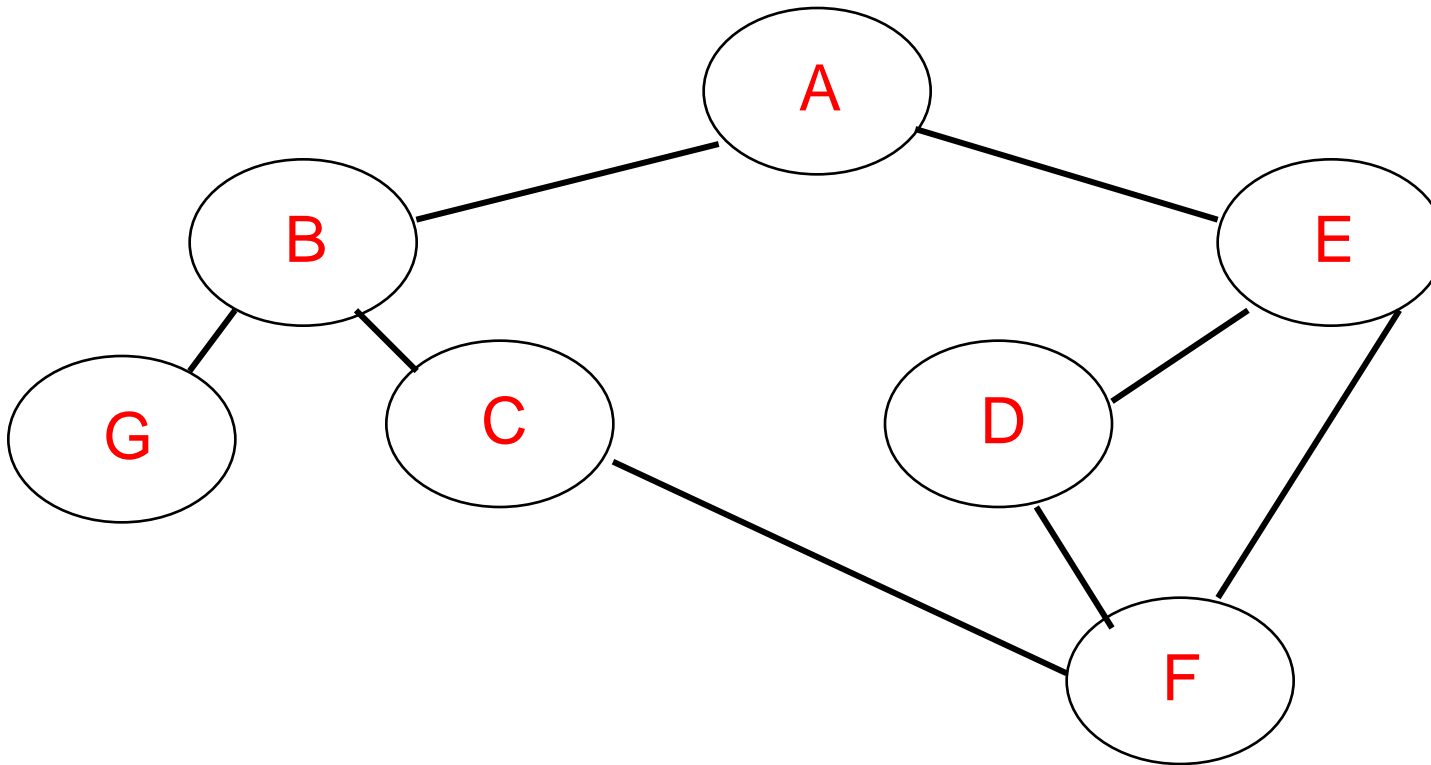
E, D, C marked, so not queued again.



# Example



Queue: **A B E C G D F**

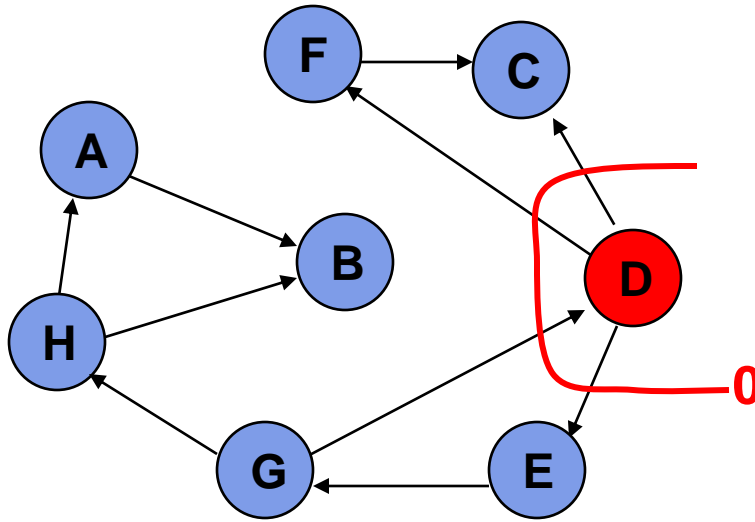


Done. We have explored the graph in order:

**A B E C G D F**

# Overview

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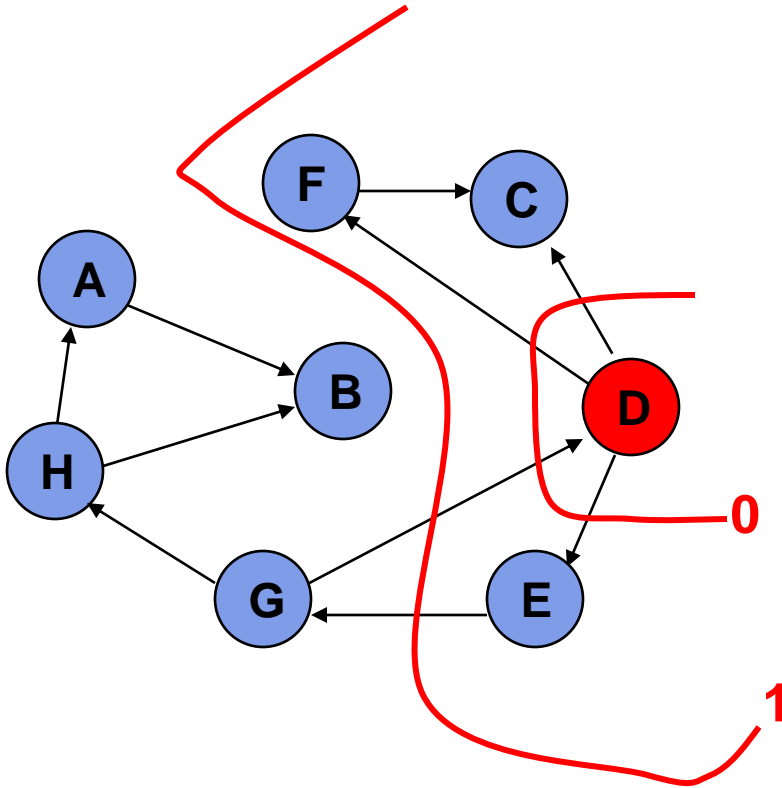


Breadth-first search starts with given node

**Task: Conduct a breadth-first search of the graph starting with node D**



# Overview



Breadth-first search starts with given node

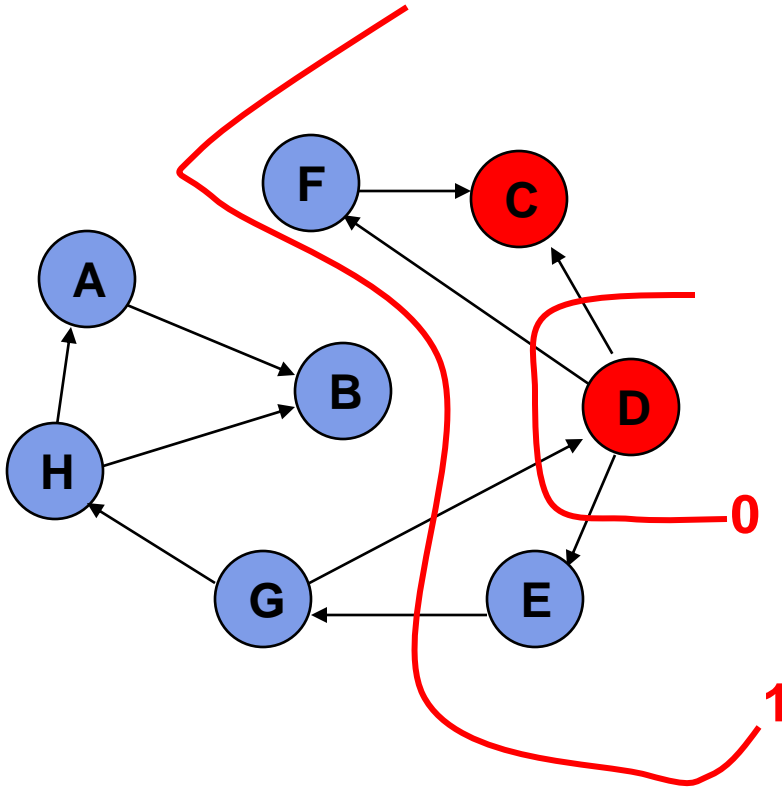
Then visits nodes adjacent in some specified order (e.g., **alphabetical**)

Like ripples in a pond

**Nodes visited: D**



# Overview



Breadth-first search starts with given node

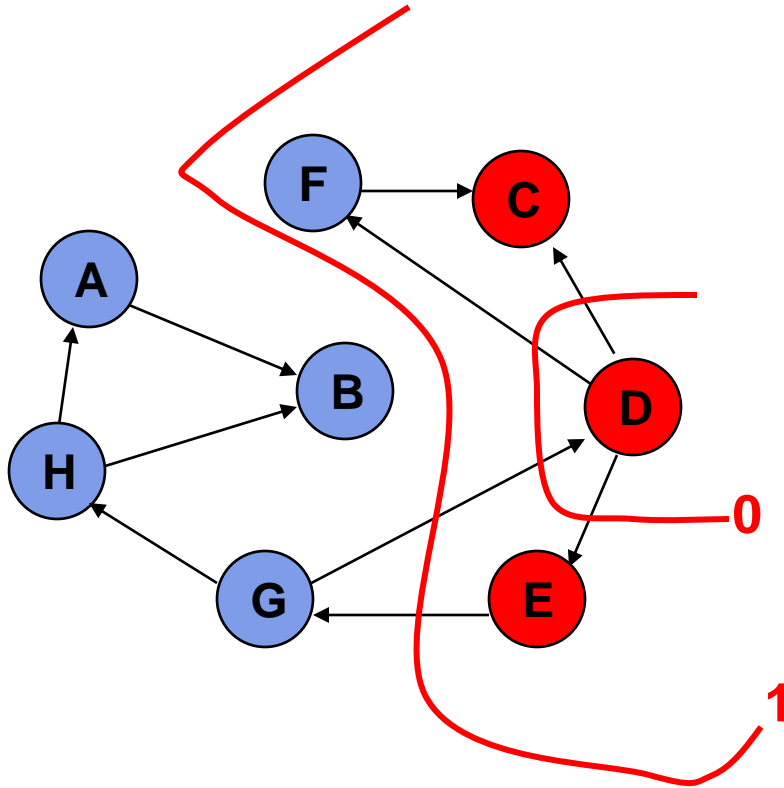
Then visits nodes adjacent in some specified order (e.g., **alphabetical**)

Like ripples in a pond

**Nodes visited: D, C**



# Overview



Breadth-first search starts with given node

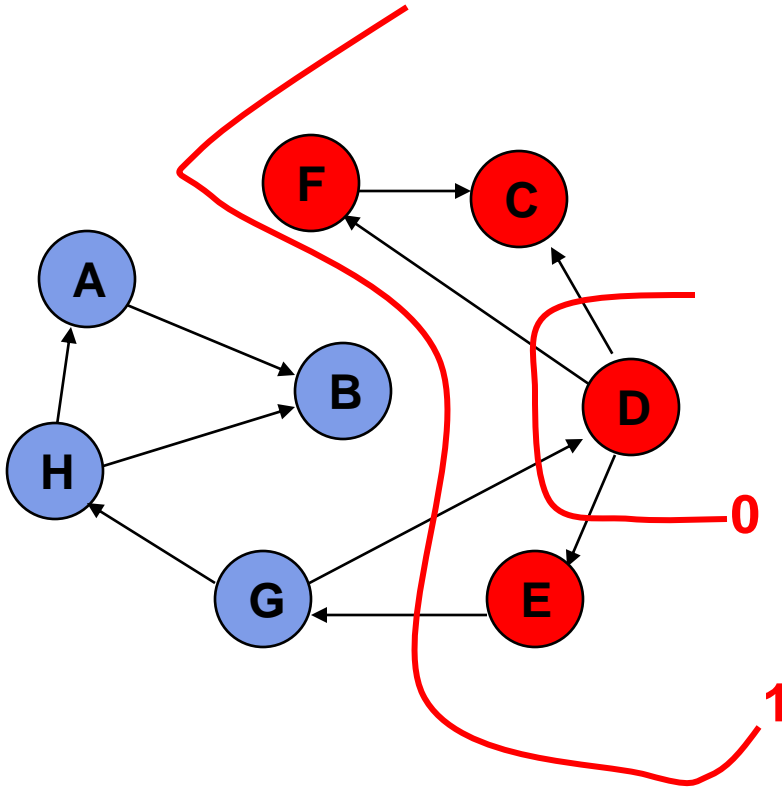
Then visits nodes adjacent in some specified order (e.g., alphabetical)

Like ripples in a pond

**Nodes visited: D, C, E**



# Overview



Breadth-first search starts with given node

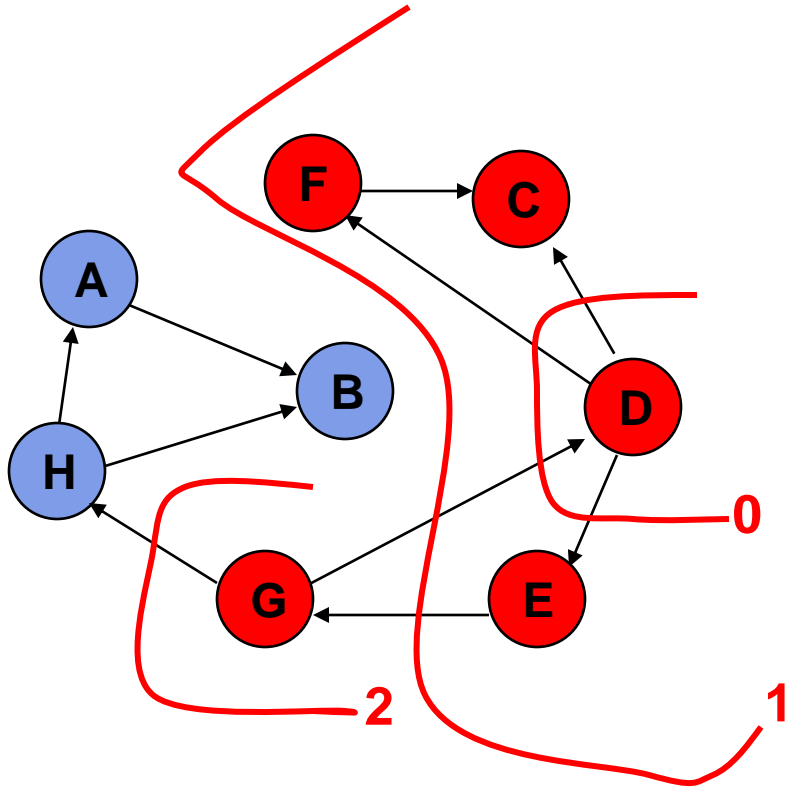
Then visits nodes adjacent in some specified order (e.g., alphabetical)

Like ripples in a pond

**Nodes visited: D, C, E, F**

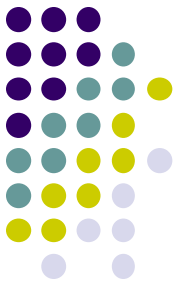


# Overview

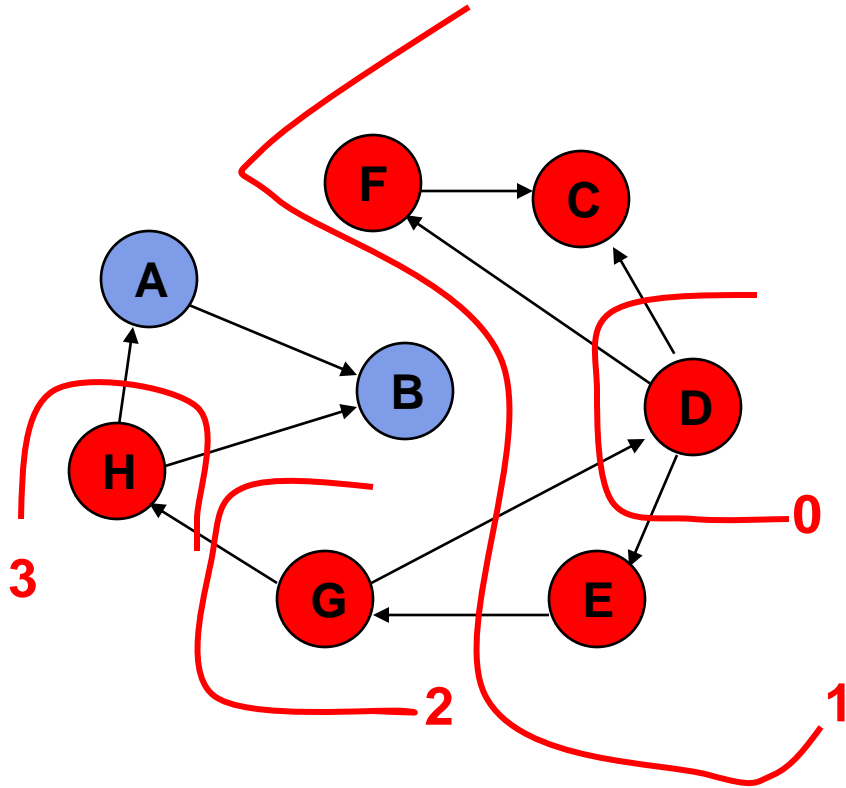


When all nodes in ripple are visited,  
visit nodes in next ripples

**Nodes visited: D, C, E, F, G**



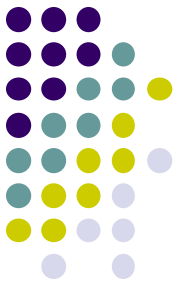
# Overview



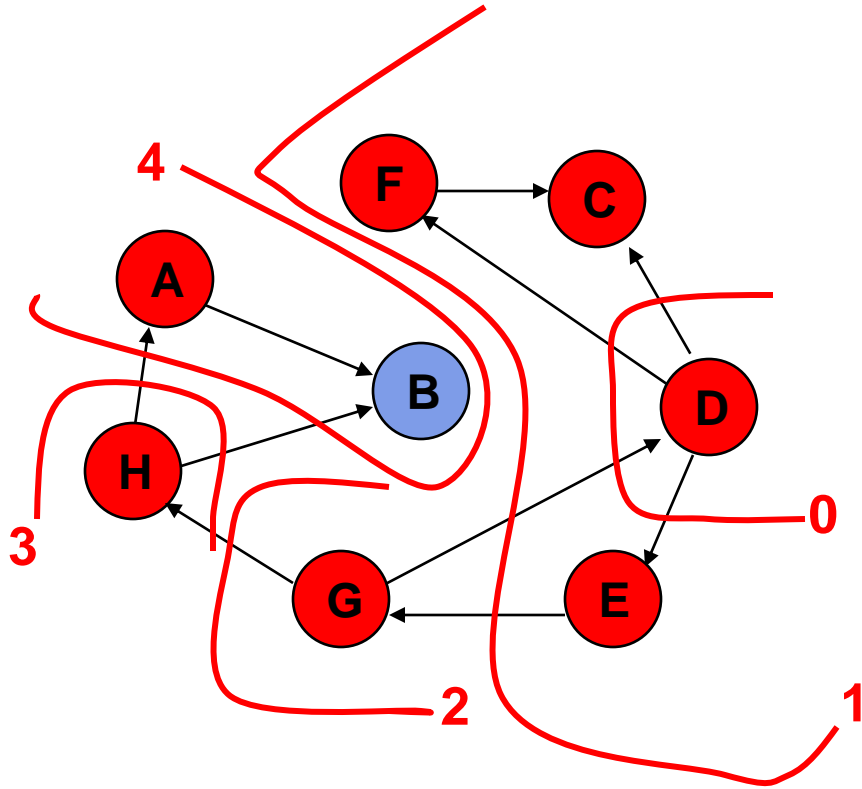
When all nodes in ripple are visited,  
visit nodes in next ripples

**Nodes visited: D, C, E, F, G, H**



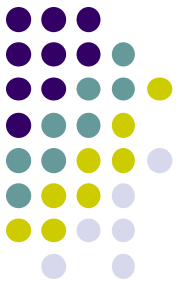


# Overview

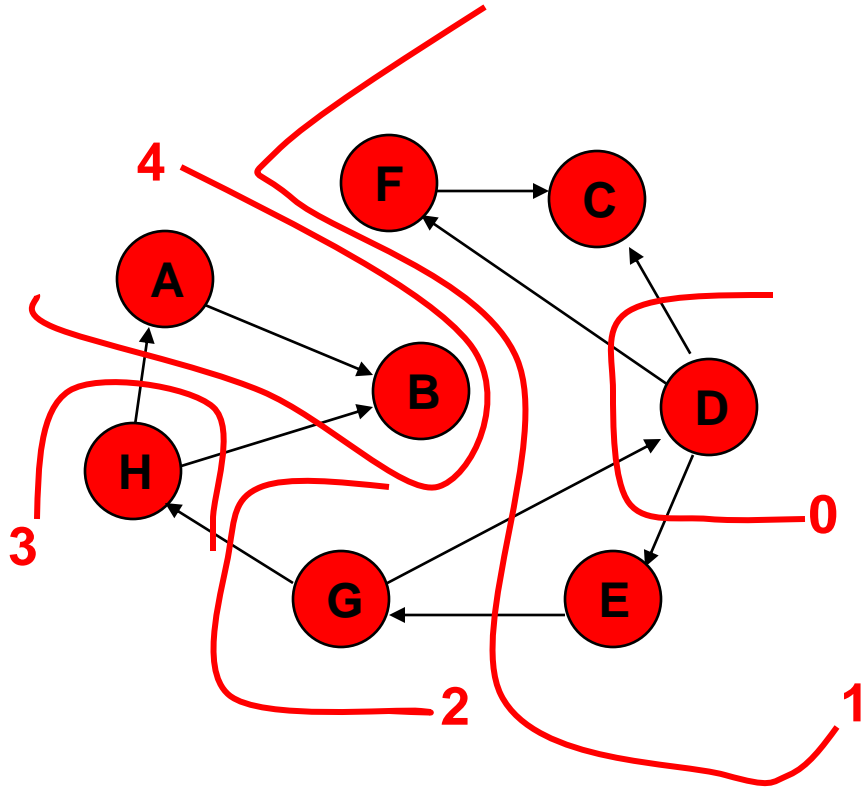


When all nodes in ripple are visited,  
visit nodes in next ripples

**Nodes visited: D, C, E, F, G, H, A**



# Overview

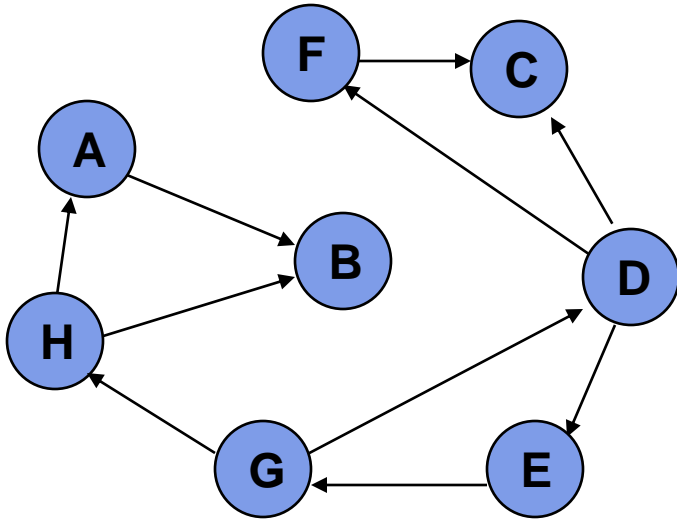


When all nodes in ripple are visited,  
visit nodes in next ripples

**Nodes visited: D, C, E, F, G, H, A, B**



# Walk-Through



Enqueued Array

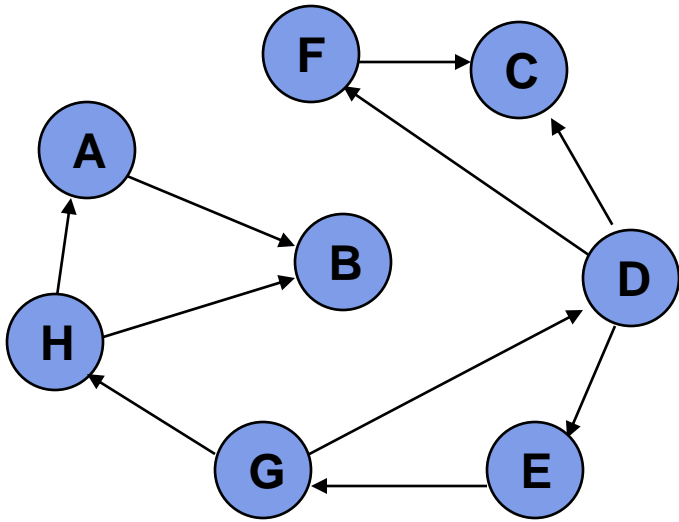
A	
B	
C	
D	
E	
F	
G	
H	

Q →

How is this accomplished? Simply replace the stack with a **queue**! Rules: (1) Maintain an *enqueued* array. (2) Visit node when *dequeued*.



# Walk-Through



Nodes visited:

Enqueued Array

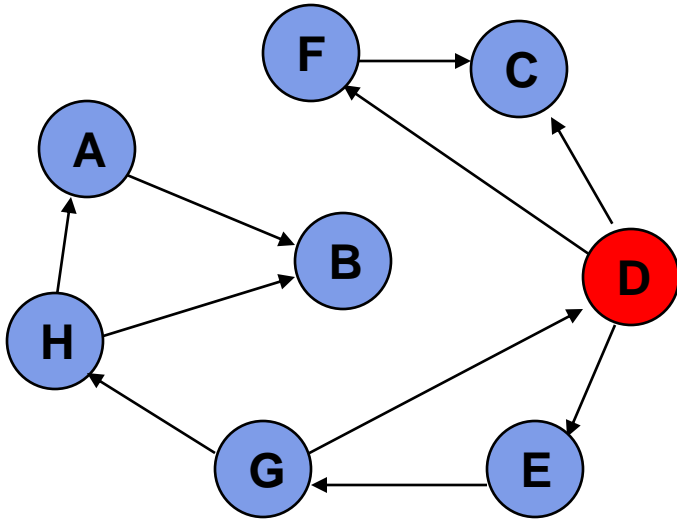
A	
B	
C	
D	✓
E	
F	
G	
H	

**Q → D**

**Enqueue D. Notice, D not yet visited.**



# Walk-Through



Nodes visited: D

Enqueued Array

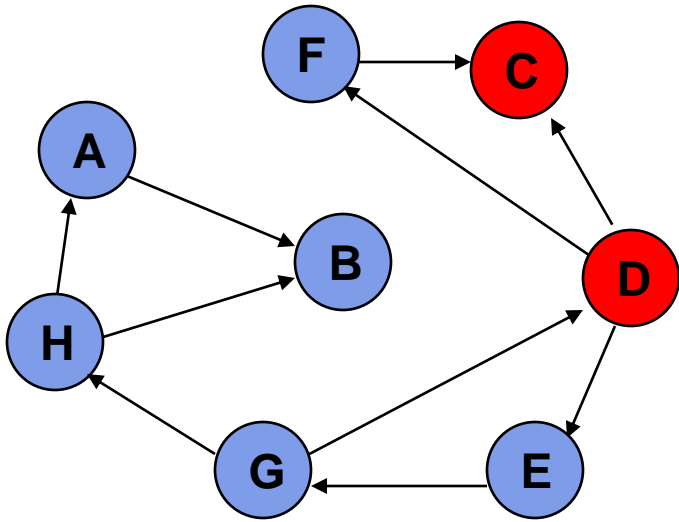
A	
B	
C	√
D	√
E	√
F	√
G	
H	

**Q → C → E → F**

**Dequeue D. Visit D. Enqueue unenqueued nodes adjacent to D.**



# Walk-Through



Nodes visited: D, C

Enqueued Array

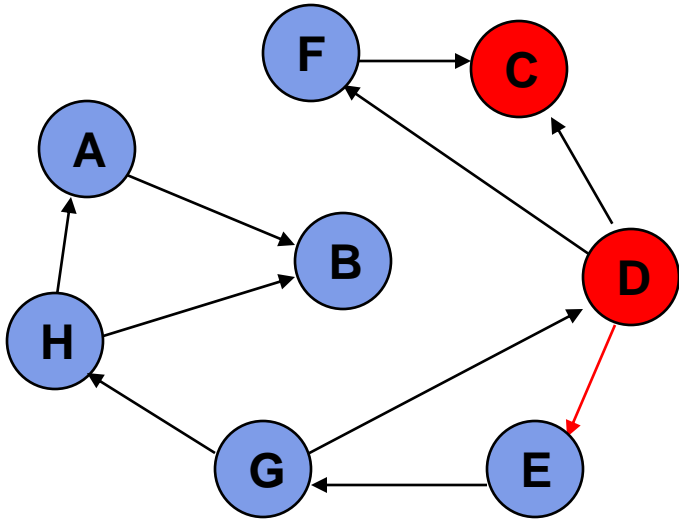
A	
B	
C	√
D	√
E	√
F	√
G	
H	

**Q → E → F**

**Dequeue C. Visit C. Enqueue unenqueued nodes adjacent to C.**



# Walk-Through



Nodes visited: D, C, E

Enqueued Array

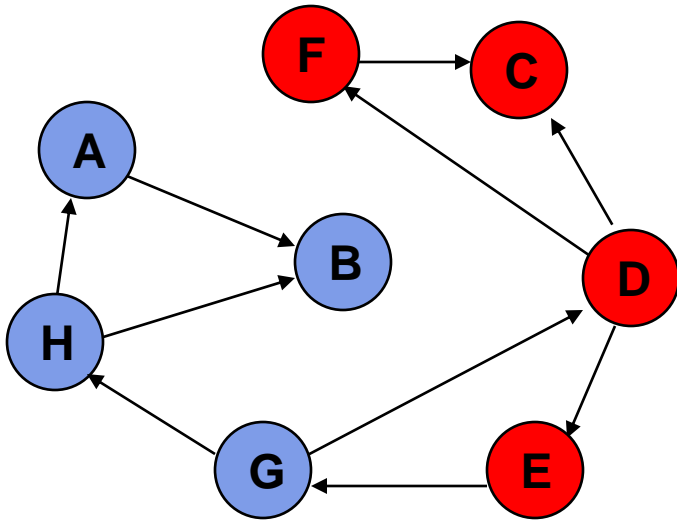
A	
B	
C	✓
D	✓
E	✓
F	✓
G	
H	

**Q → F → G**

Dequeue E. Visit E. Enqueue unenqueued nodes adjacent to E.



# Walk-Through



Nodes visited: D, C, E, F

Enqueued Array

A	
B	
C	√
D	√
E	√
F	√
G	√
H	

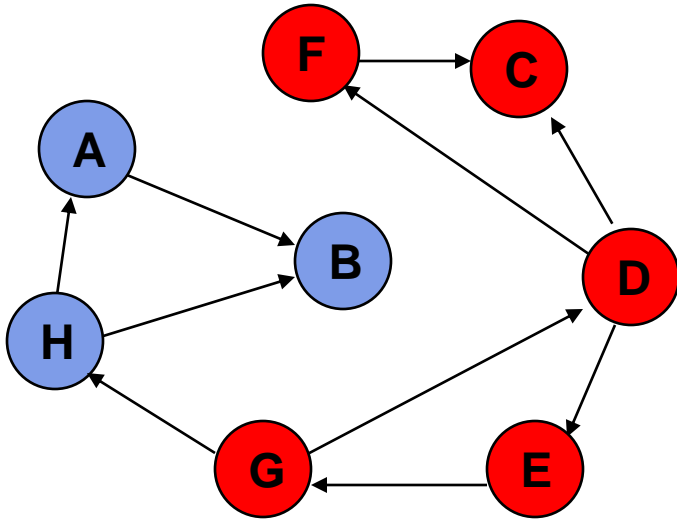
**Q → G**

**Dequeue F. Visit F. Enqueue unenqueued nodes adjacent to F.**





# Walk-Through



Nodes visited: D, C, E, F, G

Enqueued Array

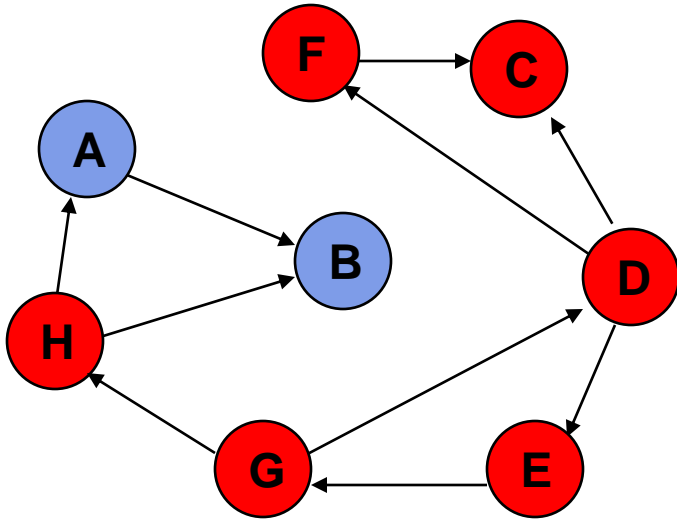
A	
B	
C	√
D	√
E	√
F	√
G	√
H	√

Q → H

Dequeue G. Visit G. Enqueue unenqueued nodes adjacent to G.



# Walk-Through



Nodes visited: D, C, E, F, G, H

Enqueued Array

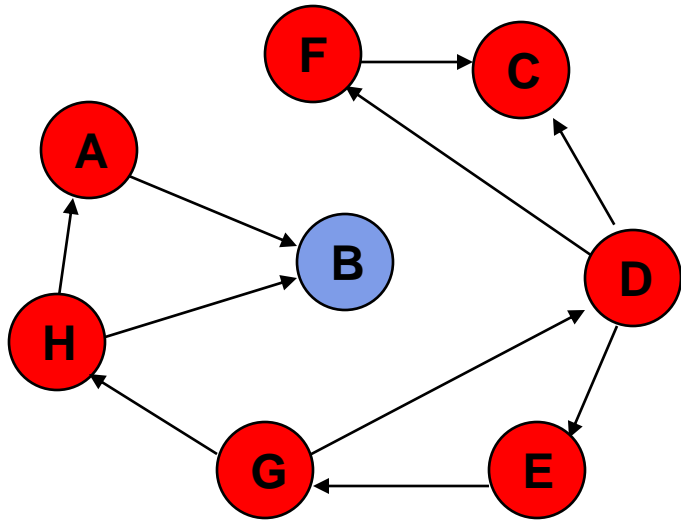
A	✓
B	✓
C	✓
D	✓
E	✓
F	✓
G	✓
H	✓

**Q → A → B**

**Dequeue H. Visit H. Enqueue unenqueued nodes adjacent to H.**



# Walk-Through



Nodes visited: D, C, E, F, G, H, A

Enqueued Array

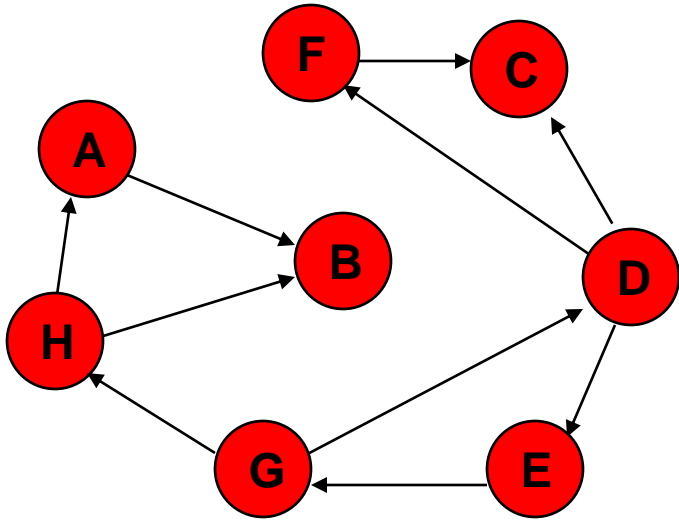
A	√
B	√
C	√
D	√
E	√
F	√
G	√
H	√

**Q → B**

**Dequeue A. Visit A. Enqueue unenqueued nodes adjacent to A.**



# Walk-Through



Nodes visited: D, C, E, F, G, H, A, B

Enqueued Array

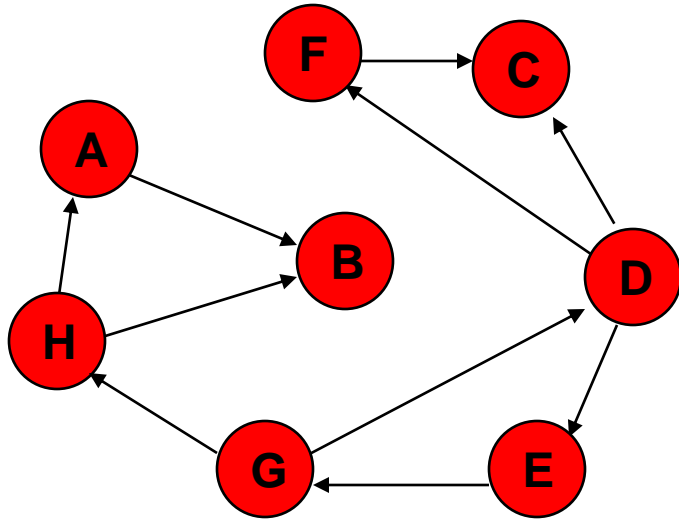
A	√
B	√
C	√
D	√
E	√
F	√
G	√
H	√

**Q empty**

**Dequeue B. Visit B. Enqueue unenqueued nodes adjacent to B.**



# Walk-Through



Nodes visited: D, C, E, F, G, H, A, B

Enqueued Array

A	✓
B	✓
C	✓
D	✓
E	✓
F	✓
G	✓
H	✓

**Q empty**

**Q empty. Algorithm done.**



# Breadth First Search Algorithm

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Given  $G = (V, E)$  and all  $v$  in  $V$  are marked unvisited,

Select one  $v$  in  $V$  and mark as visited;

Enqueue  $v$  in  $Q$

While not is\_empty( $Q$ )

{

$x = \text{front}(Q)$ ; dequeue( $Q$ );

    For each  $y$  in adjacent ( $x$ ) if unvisited ( $y$ )

{

        Mark( $y$ ); enqueue  $y$  in  $Q$ ;

        Process ( $x, y$ ) ;

}



# Thank you

# ???